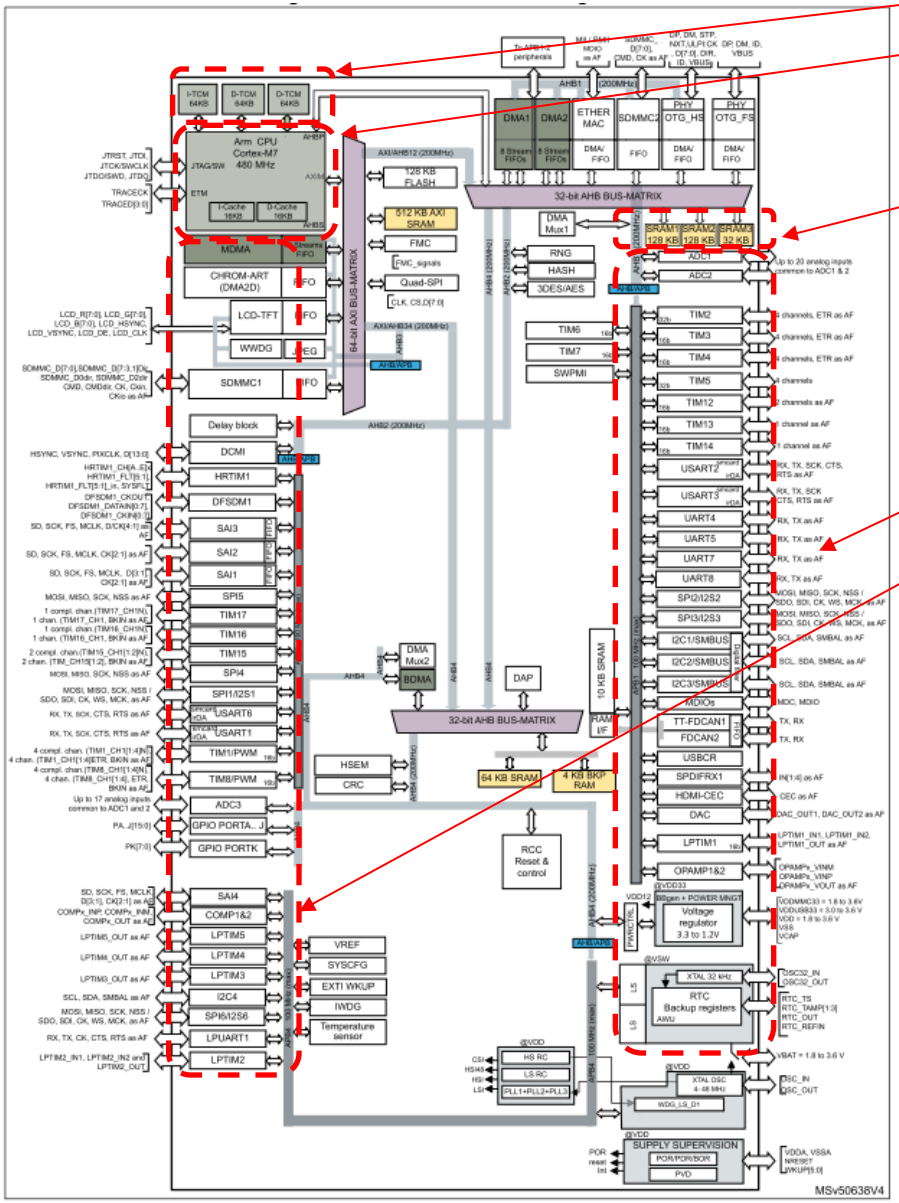
STM32H750B-DK Discovery Kit

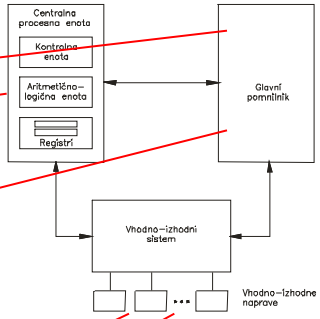
Vhodno / izhodne naprave

GPIO Krmilnik II

Utripanje LED diode

STM32H750XB

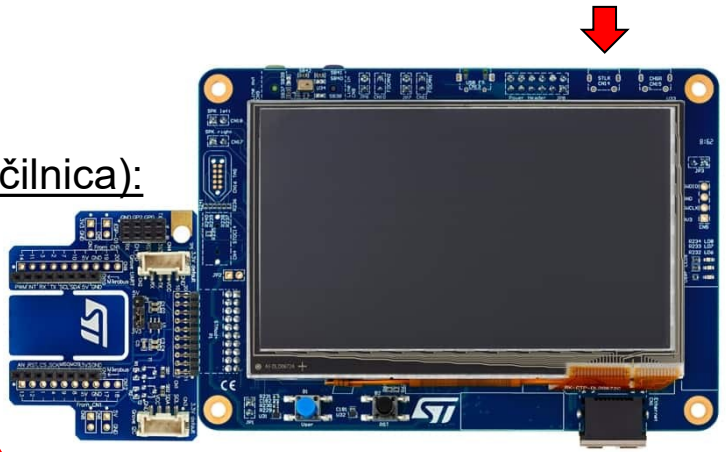




Delo na STM32H7 razvojnem sistemu

Priključitev :

- **Mikro USB** priklop na **daljši stranici (srednji !!!)**



Poseben začetni projekt (github) in info za *STM32H7* (e-učilnica):

- ***dodajanje vsebine (Main.s):***

CubeIDEWorkspace - stm32h7-asm/Core/Src/Main.s - STM32CubeIDE

File Edit Source Refactor Navigate Search Project Run Window Help

Project Explorer

- CubeIDE_Workspace
  - stm32f4-asm-qemu
- Delo
  - ARM9Template
  - stm32f4-asm (in STM32AsmTemplate)
  - ARM9Template.zip
- Node_V4 (in node_v4)
- Sluzba
  - CAN_IEX_Module
  - ORLab-STM32H7
    - stm32h7-asm
      - Binaries
      - Includes
      - Core
        - Src
          - Main.s
        - Startup
          - startup_stm32h750xbhx.s
      - Debug
      - out
      - makefile
      - README.md
      - STM32H750X.svd
      - STM32H750XBHX_FLASH.ld
      - STM32H750XBHX_RAM.ld
    - README.md
  - RALab-STM32H7
    - stm32h7-asm_RA_LED
    - README.md
  - STM32_USB_Key_AdvDebug
  - STM32_USB_Key_FreeRTOS_AdvDebug
  - STM32CubeIDE_Adv_Debug
  - STM32F4_Discovery_VIN_Projects

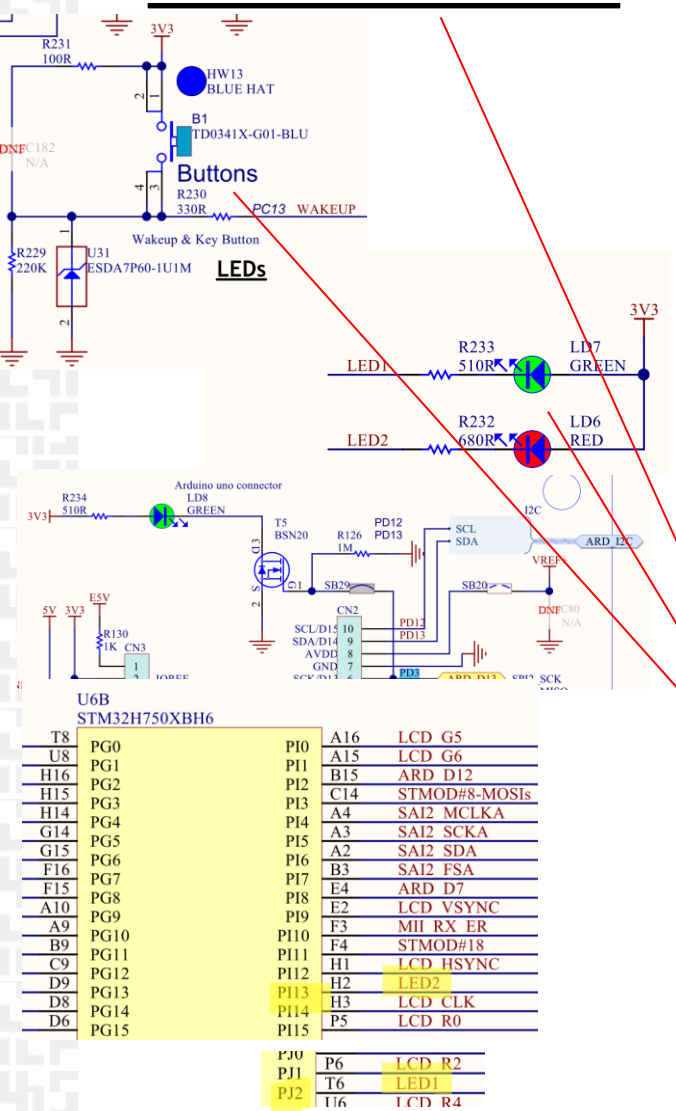
Main.s × startup_stm32h750xbhx.s

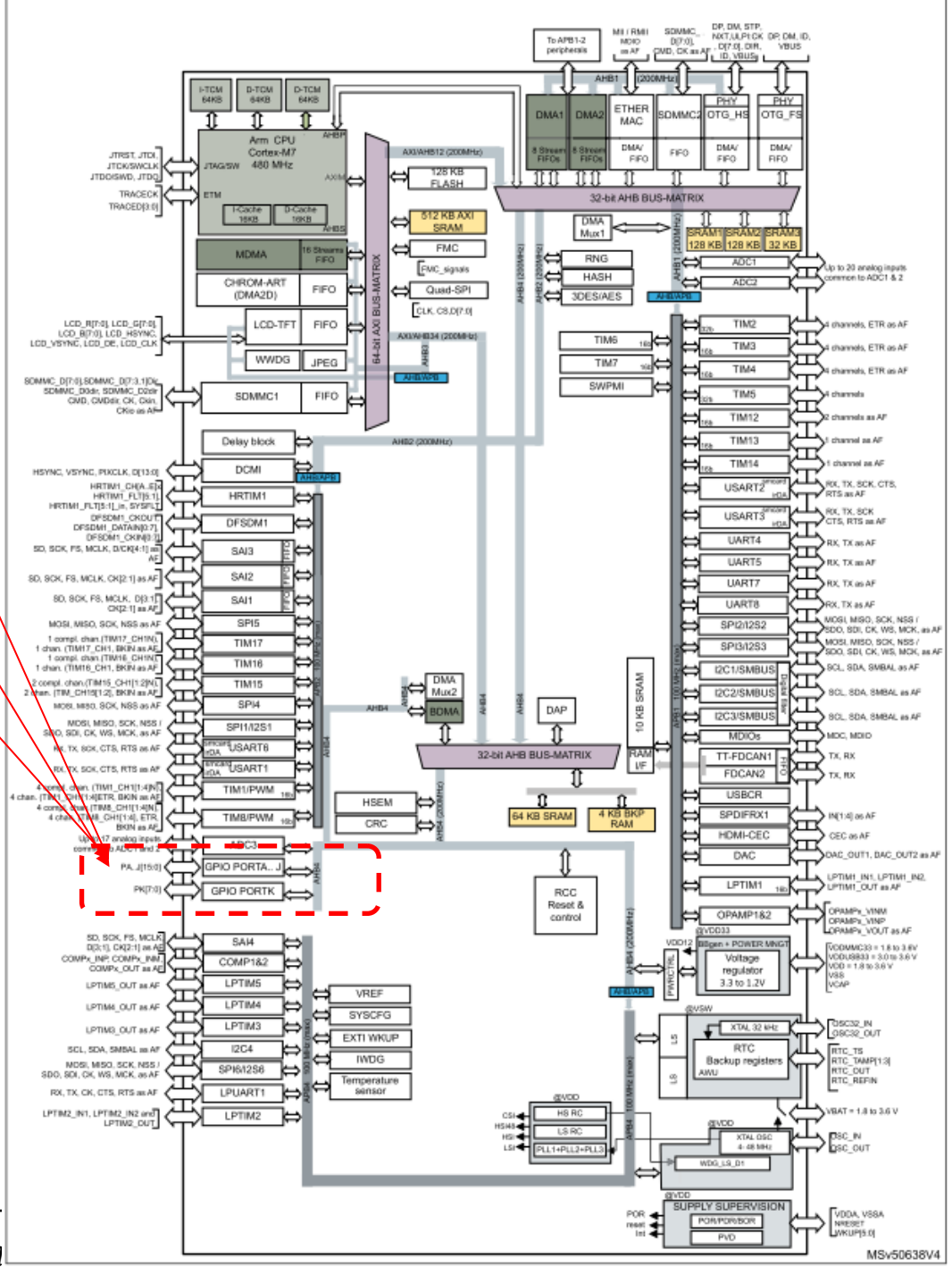
```
12
13 ////////////////////////////////////////////////////////////////////////////
14 // Definitions
15 ////////////////////////////////////////////////////////////////////////////
16 // Definitions section. Define all the registers and
17 // constants here for code readability.
18
19 // Constants
20
21
22 // Start of data section
23         .data
24
25         .align
26
27 STEV1:  .word   0x10    // 32-bitna spr.
28 STEV2:  .word   0x40    // 32-bitna spr.
29 VSOTA:  .word   0       // 32-bitna spr.
30
31
32 // Start of text section
33         .text
34
35         .type  main, %function
36         .global main
37
38         .align
39 main:
40         ldr r0, =STEV1   // Naslov od STEV1 -> r0
41         ldr r1, [r0]     // Vsebina iz naslova v r0 -> r1
42
43         ldr r0, =STEV2   // Naslov od STEV1 -> r0
44         ldr r2, [r0]     // Vsebina iz naslova v r0 -> r2
45
46         add r3,r1,r2     // r1 + r2 -> r3
47
48         ldr r0, =VSOTA   // Naslov od STEV1 -> r0
49         str r3,[r0]      // iz registra r3 -> na naslov v r0
50
51 __end:  b    __end
52
```

--------- Razvojni sistem STM32H750-DK ----------

- STM32H750B-DK Discovery kit with STM32H750XB MCU
- ORLab-STM32H7 - GitHub repozitorij
- User Manual Discovery kit stm32h750xb Uploaded 11/11/22, 10.15
- DataSheet_stm32h750xb Uploaded 11/11/22, 10.16
- Reference Manual rm0433-stm32h750xb Uploaded 11/11/22, 10.17
- Programming_Manual_pm0253-stm32h750xb Uploaded 11/11/22, 10.17
- Errata_es0396-stm32h750xb Uploaded 11/11/22, 10.19

GPIO Krmilnik





LED: rdeča PI13, zelena PJ2
zelena PD3

Vir: RM0433 Reference manual

Strani: 131, 455, 527-545

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RM0433
Reference manual

STM32H742, STM32H743/753 and STM32H750 Value line advanced Arm®-based 32-bit MCUs

11 General-purpose I/Os (GPIO) 527
11.1 Introduction 527
11.2 GPIO main features 527
11.3 GPIO functional description 530
11.3.1 General-purpose I/O (GPIO) 530
11.3.2 I/O pin alternate function multiplexer and mapping 531
11.3.3 I/O port control registers

Table 8. Register boundary addresses(1)

Boundary address	Peripheral	Bus	Register map
0x58027000 - 0x580273FF	RAMECC3		Section 3.4: RAMECC registers
0x58026400 - 0x580267FF	HSEM		Section 10.4: HSEM registers
0x58026000 - 0x580263FF	ADC3		Section 25.7: ADC common registers
0x58025800 - 0x58025BFF	DMAMUX2		Section 17.6: DMAMUX registers
0x58025400 - 0x580257FF	BDMA		Section 16.6: BDMA registers
0x58024C00 - 0x58024FFF	CRC		Section 21.4: CRC registers
0x58024800 - 0x58024BFF	PWR		Section 6.8: PWR register description
0x58024400 - 0x580247FF	RCC		Section 8.7: RCC register description
0x58022800 - 0x58022BFF	GPIOK		Section 11.4: GPIO registers
0x58022400 - 0x580227FF	GPIOJ	AHB4 (D3)	Section 11.4: GPIO registers
0x58022000 - 0x580223FF	GPIOI		Section 11.4: GPIO registers
0x58021C00 - 0x58021FFF	GPIOH		Section 11.4: GPIO registers
0x58021800 - 0x58021BFF	GPIOG		Section 11.4: GPIO registers
0x58021400 - 0x580217FF	GPIOF		Section 11.4: GPIO registers
0x58021000 - 0x580213FF	GPIOE		Section 11.4: GPIO registers
0x58020C00 - 0x58020FFF	GPIOD		Section 11.4: GPIO registers
0x58020800 - 0x58020BFF	GPIOC		Section 11.4: GPIO registers
0x58020400 - 0x580207FF	GPIOB		Section 11.4: GPIO registers
0x58020000 - 0x580203FF	GPIOA		Section 11.4: GPIO registers

RM0433 Rev 7 131/3319

11 General-purpose I/Os (GPIO)

11.1 Introduction

Each general-purpose I/O port has four 32-bit configuration registers (GPIOx_MODER, GPIOx_OTYPER, GPIOx_OSPEEDR and GPIOx_PUPDR), two 32-bit data registers (GPIOx_IDR and GPIOx_ODR) and a 32-bit set/reset register (GPIOx_BSRR). In addition all GPIOs have a 32-bit locking register (GPIOx_LCKR) and two 32-bit alternate function selection registers (GPIOx_AFRH and GPIOx_AFRL).

8.7.43 RCC AHB4 Clock Register (RCC_AHB4ENR)

This register can be accessed via two different offset address.

Table 68. RCC_AHB4ENR address offset and reset value

Register Name	Address Offset	Reset Value
RCC_AHB4ENR	0x0E0	0x0000 0000
RCC_C1_AHB4ENR	0x140	

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rm0433-stm32h750_GPIO_Ch11.pdf

Vir: RM0433 Reference manual

8.7.43 RCC AHB4 Clock Register (RCC_AHB4ENR)

This register can be accessed via two different offset address.

Bit 9 **GPIOJEN**: GPIOJ peripheral clock enable
Set and reset by software.
0: GPIOJ peripheral clock disabled (default after reset)
1: GPIOJ peripheral clock enabled

Bit 8 **GPIOIEN**: GPIOI peripheral clock enable
Set and reset by software.
0: GPIOI peripheral clock disabled (default after reset)
1: GPIOI peripheral clock enabled

Table 68. RCC_AHB4ENR address offset and reset value

Register Name	Address Offset	Reset Value
RCC_AHB4ENR	0x0E0	0x0000 0000
RCC_C1_AHB4ENR	0x140	

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
Res.	Res.	Res.	BKPRAMEN	Res.	Res.	HSEMEN	ADC3EN	Res.	Res.	BDMAEN	Res.	CRCEN	Res.	Res.	Res.
			rw			rw	rw			rw		rw			

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Res.	Res.	Res.	Res.	Res.	GPIOKEN	GPIOJEN	GPIOIEN	GPIOHEN	GPIOGEN	GPIOFEN	GPIOEEN	GPIODEN	GPIOCEN	GPIOBEN	GPIOAEN
					rw	rw	rw	rw	rw	rw	rw	rw	rw	rw	rw

Vir: RM0433 Reference manual

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RM0090
Reference manual

STM32F405/415, STM32F407/417, STM32F427/437 and STM32F429/439 advanced Arm®-based 32-bit MCUs

Table 8. Register boundary addresses(1)

Boundary address	Peripheral	Bus	Register map
0x58027000 - 0x580273FF	RAMECC3		*Section 3.4: RAMECC registers*
0x58026400 - 0x580267FF	HSEM	AHB4 (D3)	*Section 10.4: HSEM registers*
0x58026000 - 0x580263FF	ADC3		*Section 25.7: ADC common registers*
0x58025800 - 0x58025BFF	DMAMUX2		*Section 17.6: DMAMUX registers*
0x58025400 - 0x580257FF	BDMA		*Section 16.6: BDMA registers*
0x58024C00 - 0x58024FFF	CRC		*Section 21.4: CRC registers*
0x58024800 - 0x58024BFF	PWR		*Section 6.8: PWR register description*
0x58024400 - 0x580247FF	RCC		*Section 8.7: RCC register description*
0x58022800 - 0x58022BFF	GPIOK		*Section 11.4: GPIO registers*
0x58022400 - 0x580227FF	GPIOJ		*Section 11.4: GPIO registers*
0x58022000 - 0x580223FF	GPIOI		*Section 11.4: GPIO registers*
0x58021C00 - 0x58021FFF	GPIOH		*Section 11.4: GPIO registers*
0x58021800 - 0x58021BFF	GPIOG		*Section 11.4: GPIO registers*
0x58021400 - 0x580217FF	GPIOF		*Section 11.4: GPIO registers*
0x58021000 - 0x580213FF	GPIOE		*Section 11.4: GPIO registers*
0x58020C00 - 0x58020FFF	GPIOD		*Section 11.4: GPIO registers*
0x58020800 - 0x58020BFF	GPIOC		*Section 11.4: GPIO registers*
0x58020400 - 0x580207FF	GPIOB		*Section 11.4: GPIO registers*
0x58020000 - 0x580203FF	GPIOA		*Section 11.4: GPIO registers*

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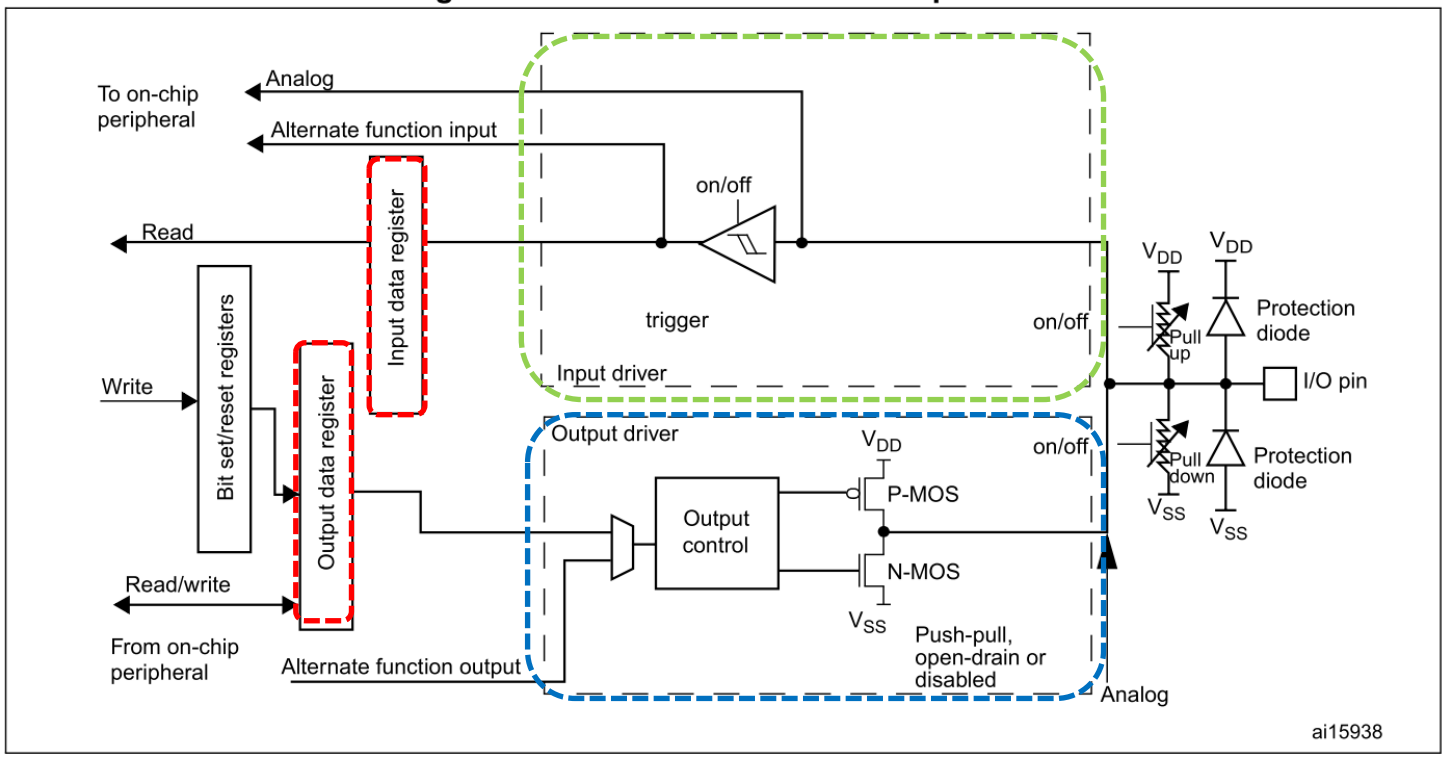
GPIO krmilnik – vhod/izhod

Figure 70. Basic structure of an I/O port bit



Osnovni registri za GPIO priključke :

RCC_AHBxENR : vklop urinega signala (enote) : Port I: RCC_AHB4ENR(b_8=1 .. Port I Enable)

MODER (Mode Register): 00: Input (reset) / 01: General purpose output mode

OTYPER (Output TYPE Register): 0: Output push-pull (reset) / 1: Output open-drain

OSPEEDR (Output SPEED Register): 00 – Low speed (reset) .. 11: Very high speed

PUPDR (Pull Up/Down Register): 00 – No pull (reset) .. 01: Pull-Up .. 10: Pull-Down

IDR (Input Data Register): stanje vhoda 1 / 0

ODR (Output Data Register): stanje izhoda 1 / 0

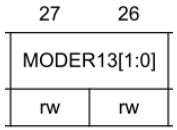
GPIO krmilnik – izhod *(Registri za nastavitve delovanja)*

RCC_AHB4ENR(Peripheral Clock Register):

Bit 8 **GPIOIEN:** GPIOI peripheral clock enable
Set and reset by software.
0: GPIOI peripheral clock disabled (default after reset)
1: GPIOI peripheral clock enabled

MODER (Mode Register):

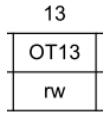
Bits 31:0 **MODER[15:0][1:0]:** Port x configuration I/O pin y (y = 15 to 0)
These bits are written by software to configure the I/O mode.
00: Input mode
01: General purpose output mode
10: Alternate function mode
11: Analog mode (reset state)



OTYPER (Output TYPE Register):

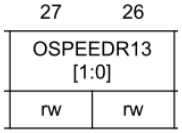
Bits 31:16 Reserved, must be kept at reset value.

Bits 15:0 **OT[15:0]:** Port x configuration I/O pin y (y = 15 to 0)
These bits are written by software to configure the I/O output type.
0: Output push-pull (reset state)
1: Output open-drain



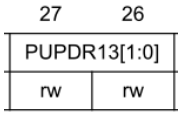
OSPEEDR (Output SPEED Register):

Bits 31:0 **OSPEEDR[15:0][1:0]**: Port x configuration I/O pin y (y = 15 to 0)
These bits are written by software to configure the I/O output speed.
00: Low speed
01: Medium speed
10: High speed
11: Very high speed



PUPDR (Pull Up/Down Register):

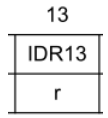
Bits 31:0 **PUPDR[15:0][1:0]:** Port x configuration I/O pin y (y = 15 to 0)
These bits are written by software to configure the I/O pull-up or pull-down
00: No pull-up, pull-down
01: Pull-up
10: Pull-down
11: Reserved



IDR (Input Data Register): stanje vhoda 1 / 0

Bits 31:16 Reserved, must be kept at reset value.

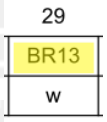
Bits 15:0 **IDR[15:0]:** Port x input data I/O pin y (y = 15 to 0)
These bits are read-only. They contain the input value of the corresponding I/O port.



ODR (Output Data Register): stanje izhoda 1 / 0

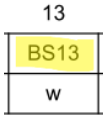
Bits 31:16 Reserved, must be kept at reset value.

Bits 15:0 **ODR[15:0]:** Port output data I/O pin y (y = 15 to 0)
These bits can be read and written by software.
Note: For atomic bit set/reset, the ODR bits can be individually set and/or reset by writing to the GPIOx_BSRR register (x = A..F).



Bits 31:16 **BR[15:0]:** Port x reset I/O pin y (y = 15 to 0)
These bits are write-only. A read to these bits returns the value 0x0000.
0: No action on the corresponding ODRx bit
1: Resets the corresponding ODRx bit
Note: If both BSx and BRx are set, BSx has priority.

Bits 15:0 **BS[15:0]:** Port x set I/O pin y (y = 15 to 0)
These bits are write-only. A read to these bits returns the value 0x0000.
0: No action on the corresponding ODRx bit
1: Sets the corresponding ODRx bit



GPIO krmilnik – izhod *(Registri za določanje stanja izhodov)*

2 možnosti za določanje stanja izhodov:

1. Spreminjanje bitov v registru ODR
   Read-Modify-Write operacija na registru ODR
   ODR (Output Data Register): stanje izhoda 1 / 0

Bits 31:16 Reserved, must be kept at reset value.

Bits 15:0 **ODR[15:0]:** Port output data I/O pin y (y = 15 to 0)
These bits can be read and written by software.
Note: For atomic bit set/reset, the ODR bits can be individually set and/or reset by writing to the GPIOx_BSRR register (x = A..F).

13
ODR13
rw

2. Spreminjanje bitov v registru ODR s pomočjo vpisa v register BSRR
   Write operacija v register BSRR -> sprememba bitov v registru ODR
   + atomična operacija
   BSRR (Port Set/Reset Register): stanje izhoda 1 / 0

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
BR15	BR14	BR13	BR12	BR11	BR10	BR9	BR8	BR7	BR6	BR5	BR4	BR3	BR2	BR1	BR0
w	w	w	w	w	w	w	w	w	w	w	w	w	w	w	w
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
BS15	BS14	BS13	BS12	BS11	BS10	BS9	BS8	BS7	BS6	BS5	BS4	BS3	BS2	BS1	BS0
w	w	w	w	w	w	w	w	w	w	w	w	w	w	w	w

29
BR13
w

Bits 31:16 **BR[15:0]:** Port x reset I/O pin y (y = 15 to 0)
These bits are write-only. A read to these bits returns the value 0x0000.
0: No action on the corresponding ODRx bit
1: Resets the corresponding ODRx bit
Note: If both BSx and BRx are set, BSx has priority.

Bits 15:0 **BS[15:0]:** Port x set I/O pin y (y = 15 to 0)
These bits are write-only. A read to these bits returns the value 0x0000.
0: No action on the corresponding ODRx bit
1: Sets the corresponding ODRx bit

13
BS13
w

GPIO krmilnik – krmiljenje izhodov

Potrebni koraki za krmiljenje izhoda:

1. RCC_AHB4ENR(Peripheral Clock Register): b_8=1 .. Port I Enable
2. **MODER (Mode Register): 01: General purpose output mode**
3. Default vrednosti že ustrezne v registrih :
   - **OTYPER (Output TYPE Register): 0: Output push-pull** (reset state)
   - **OSPEEDR (Output SPEED Register): 00 – Low speed** (reset state)
   - **PUPDR (Pull Up/Down Register): 00 – No pull** (reset state)
4. določi stanje izhoda s pisanjem v ODR ali BSRR (nastavljamo na 1/0)

Naslovi registrov:

```
// RCC   base address is 0x58024400
//   AHB4ENR register offset is 0xE0
.equ     RCC_AHB4ENR,   0x580244E0 // RCC AHB4 peripheral clock reg

.equ     GPIOI_BASE,   0x58022000  // GPIOI base address)
.equ     GPIOx_MODER,    0x00      // GPIOx port mode register
.equ     GPIOx_ODR,      0x14      // GPIOx output data register
.equ     GPIOx_BSRR,     0x18      // GPIOx port set/reset register

// Values for BSSR register - pin 13: LED is on, when GPIO is off
.equ     LEDs_OFF,       0x00002000   // Setting pin to 1 -> LED is off
.equ     LEDs_ON,        0x20000000   // Setting pin to 0 -> LED is on
```

GPIO krmilnik – krmiljenje izhodov

Potrebni koraki za krmiljenje izhoda:

1. RCC_AHB4ENR(Peripheral Clock Register): b_8=1 .. Port I Enable

```
// Enable GPIOI Peripheral Clock (bit 8 in AHB4ENR register)
ldr r6, = RCC_AHB4ENR       // Load peripheral clock reg address to r6
ldr r5, [r6]                // Read its content to r5
orr r5, #0x00000100          // Set bit 8 to enable GPIOI clock
str r5, [r6]                // Store result in peripheral clock register
```

2. **MODER (Mode Register): 01: General purpose output mode**

```
// Make GPIOI Pin13 as output pin (bits 27:26 in MODER register)
ldr r6, =GPIOI_BASE       // Load GPIOD BASE address to r6
ldr r5, [r6,#GPIOx_MODER]  // Read GPIOD_MODER content to r5
and r5, #0xF3FFFFFF          // Clear bits 27-26 for P13
orr r5, #0x04000000          // Write 01 to bits 27-26 for P13
str r5, [r6]                // Store result in GPIO MODER register
```

3. Default vrednosti že ustrezne v registrih : **OTYPER, OSPEEDR ,PUPDR**

4. določi stanje izhoda s pisanjem v BSRR (ali tudi ODR) (nastavljamo na 1/0)

```
LED_ON:
 push {r5, r6, lr}
// Set GPIOx Pins to 0 (through BSSR register)
 ldr    r6, =GPIOI_BASE       // Load GPIOI BASE address to r6
 mov    r5, #LEDs_ON
 str    r5, [r6,#GPIOx_BSRR] // Write to BSRR register
 pop {r5, r6, pc}
```

```
LED_OFF:
 push {r5, r6, lr}
// Set GPIOx Pins to 1 (through BSSR register)
 ldr    r6, =GPIOI_BASE       // Load GPIOI BASE address to r6
 mov    r5, #LEDs_OFF
 str    r5, [r6,#GPIOx_BSRR] // Write to BSRR register
 pop {r5, r6, pc}
```

GPIO krmilnik – krmiljenje izhodov – „C“

Potrebni koraki za krmiljenje izhoda:

1. RCC_AHB4ENR(Peripheral Clock Register): b_8=1 .. Port I Enable
2. **MODER (Mode Register): 01: General purpose output mode**
3. Default vrednosti že ustrezne v registrih :
   - **OTYPER (Output TYPE Register): 0: Output push-pull** (reset state)
   - **OSPEEDR (Output SPEED Register): 00 – Low speed** (reset state)
   - **PUPDR (Pull Up/Down Register): 00 – No pull** (reset state)
4. določi stanje izhoda s pisanjem v ODR ali BSRR (nastavljamo na 1/0)

Naslovi registrov:

```
#define RCC_AHB4ENR ((volatile uint32_t *)0x580244E0)

typedef struct {
     volatile uint32_t MODER;
     volatile uint32_t OTYPER;
     volatile uint32_t OSPEEDR;
     volatile uint32_t PUPDR;
     volatile uint32_t IDR;
     volatile uint32_t ODR;
     volatile uint32_t BSRR;
} GPIO_device;
```

```
#define GPIOC ((GPIO_device *)0x58020800)
#define GPIOD ((GPIO_device *)0x58020C00)
#define GPIOI ((GPIO_device *)0x58022000)
#define GPIOJ ((GPIO_device *)0x58022400)
```

https://rok-cesnovar.github.io/ORS/vaja_2.html

GPIO krmilnik – krmiljenje izhodov – „C“

Potrebni koraki za krmiljenje izhoda PD3:

1. RCC_AHB4ENR(Peripheral Clock Register): b_3=1 .. Port D Enable

```
*RCC_AHB4ENR = *RCC_AHB4ENR | (1 << 3); // postavimo GPIODEN
```

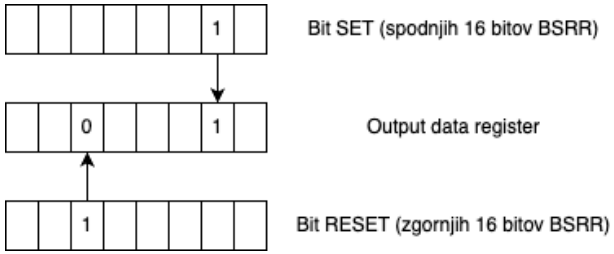
2. **MODER (Mode Register): 01: General purpose output mode**

```
// pin 3 inicializiramo kot izhod
GPIOD->MODER = GPIOD->MODER & ~(3 << (2 * 3));
GPIOD->MODER = GPIOD->MODER | (1 << (2 * 3));
```

3. Default vrednosti že ustrezne v registrih : **OTYPER, OSPEEDR ,PUPDR**

4. določi stanje izhoda s pisanjem v BSRR (ali tudi ODR) (nastavljamo na 1/0)

```
// prizgemo LED
    GPIOD->BSRR = 1 << 3;
// ugasnimo LED
    GPIOD->BSRR = 1 << (3 + 16);
```



https://rok-cesnovar.github.io/ORS/vaja_2.html

GPIO krmilnik – krmiljenje izhodov – „C“ + HAL

Potrebni koraki za krmiljenje izhoda:

1. RCC_AHB4ENR(Peripheral Clock Register): b_8=1 .. Port I Enable

```
/* GPIO Ports Clock Enable */
__HAL_RCC_GPIOI_CLK_ENABLE();
```

2. **MODER (Mode Register): 01: General purpose output mode**
3. Default vrednosti že ustrezne v registrih :

   OTYPER (Output TYPE Register): 0: Output push-pull (reset state)

   OSPEEDR (Output SPEED Register): 00 – Low speed (reset state)

   PUPDR (Pull Up/Down Register): 00 – No pull (reset state)

```
GPIO_InitTypeDef init_structure;
init_structure.Pin = GPIO_PIN_13;
init_structure.Mode = GPIO_MODE_OUTPUT_PP;
init_structure.Pull = GPIO_NOPULL;
init_structure.Speed = GPIO_SPEED_FREQ_LOW;
HAL_GPIO_Init(GPIOI, &init_structure);
```

```
#define GPIOC ((GPIO_device *)0x58020800)
#define GPIOD ((GPIO_device *)0x58020C00)
#define GPIOI ((GPIO_device *)0x58022000)
#define GPIOJ ((GPIO_device *)0x58022400)
```

4. določi stanje izhoda s pisanjem v ODR ali BSRR (nastavljamo na 1/0)

```
HAL_GPIO_WritePin(GPIOI, GPIO_PIN_13,1);
HAL_GPIO_WritePin(GPIOI, GPIO_PIN_13,0);

HAL_GPIO_TogglePin(GPIOI, GPIO_PIN_13);
```

GPIO krmilnik – krmiljenje izhodov – HAL funkcije

Definicije funkcij v HAL knjižnici:

```
__HAL_RCC_GPIOI_CLK_ENABLE();
```

```
#define __HAL_RCC_GPIOI_CLK_ENABLE() do { \
__IO uint32_t tmpreg; \
SET_BIT(RCC->AHB4ENR, RCC_AHB4ENR_GPIOIEN);\
/* Delay after an RCC peripheral clock enabling */ \
tmpreg = READ_BIT(RCC->AHB4ENR, RCC_AHB4ENR_GPIOIEN);\
UNUSED(tmpreg); \
} while(0)
```

```
GPIO_InitTypeDef init_structure;
init_structure.Pin = GPIO_PIN_13;
init_structure.Mode = GPIO_MODE_OUTPUT_PP;
init_structure.Pull = GPIO_NOPULL;
init_structure.Speed = GPIO_SPEED_FREQ_LOW;
HAL_GPIO_Init(GPIOI, &init_structure);
```

```
void HAL_GPIO_Init(GPIO_TypeDef *GPIOx, GPIO_InitTypeDef
*GPIO_Init)
{
…
/* Configure the IO Speed */
temp = GPIOx->OSPEEDR;
temp &= ~(GPIO_OSPEEDR_OSPEED0 << (position * 2U));
temp |= (GPIO_Init->Speed << (position * 2U));
GPIOx->OSPEEDR = temp;

/* Configure the IO Output Type */
temp = GPIOx->OTYPER;
temp &= ~(GPIO_OTYPER_OT0 << position) ;
temp |= (((GPIO_Init->Mode & OUTPUT_TYPE) >>
OUTPUT_TYPE_Pos) << position);
GPIOx->OTYPER = temp;
}

if ((GPIO_Init->Mode & GPIO_MODE) != MODE_ANALOG)
{
/* Configure IO Direction mode (Input, Output, Alternate or
Analog) */
temp = GPIOx->MODER;
temp &= ~(GPIO_MODER_MODE0 << (position * 2U));
temp |= ((GPIO_Init->Mode & GPIO_MODE) << (position * 2U));
GPIOx->MODER = temp;
```

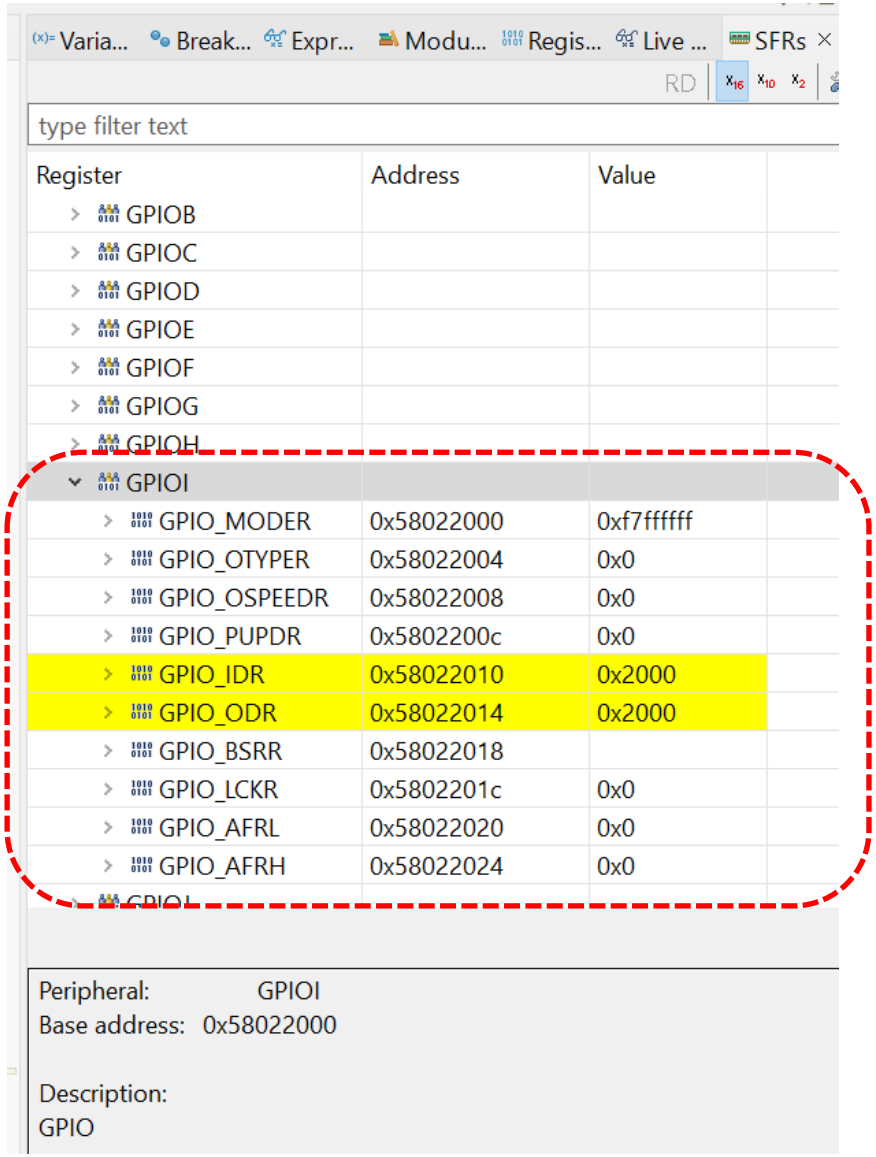
```
HAL_GPIO_WritePin(GPIOI, GPIO_PIN_13,1);
```

```
void HAL_GPIO_WritePin(GPIO_TypeDef *GPIOx, uint16_t GPIO_Pin,
GPIO_PinState PinState)
{
…
        if (PinState != GPIO_PIN_RESET){
                GPIOx->BSRR = GPIO_Pin;
        }else{
                GPIOx->BSRR = (uint32_t)GPIO_Pin <<GPIO_NUMBER;
        }
}
```

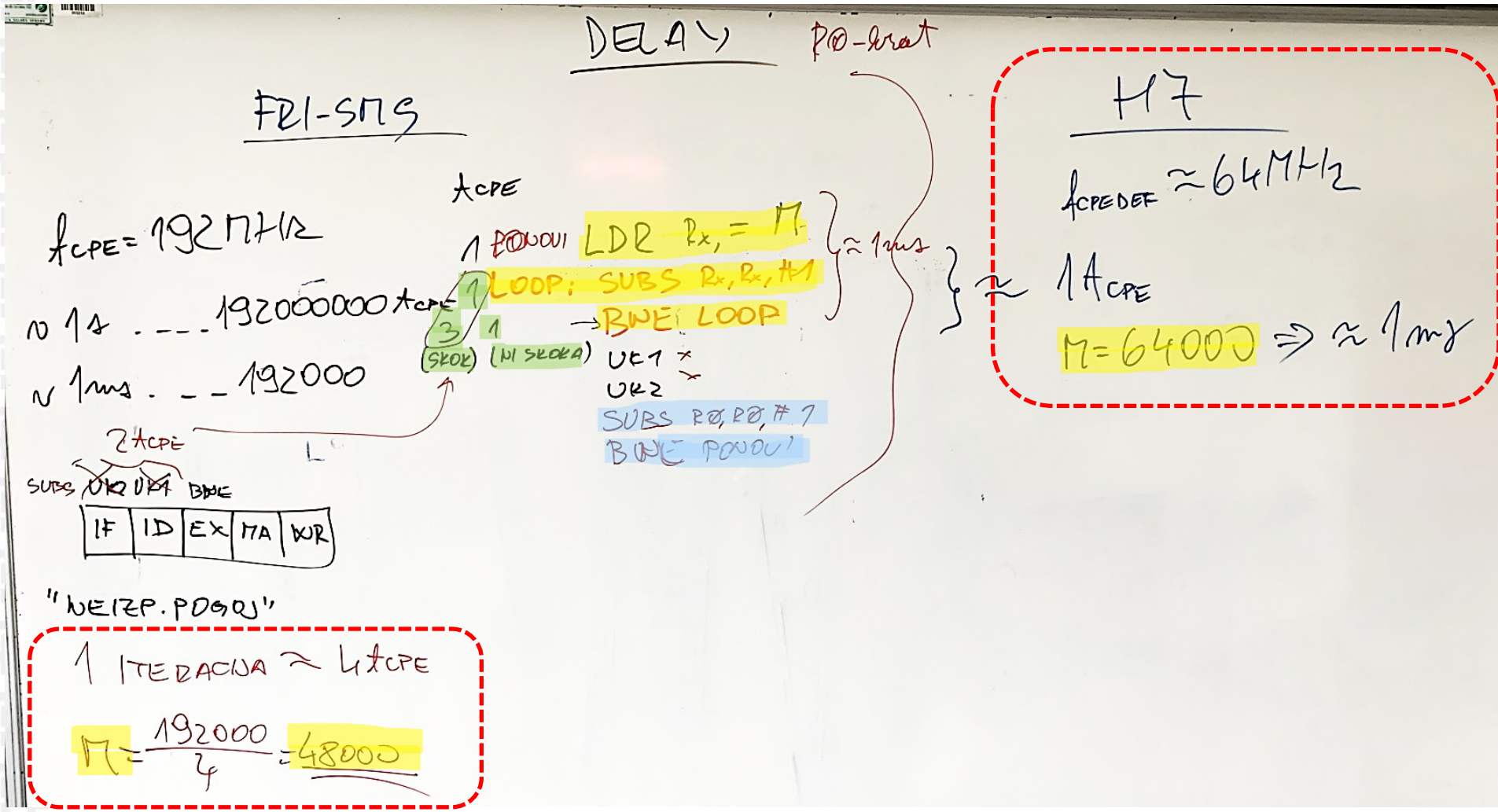
CubeIDE – Registers okno

Name	Value
General Registers	
r0	0xe
r1	0x3f95
r2	0x40
r3	0x50
r4	0x20000030
r5	0x0
r6	0x0
r7	0x0
r8	0x0
r9	0x0
r10	0x0
r11	0x0
r12	0x0
sp	0x2001fff8
lr	0x24000305
pc	0x24000344
xpsr	0x21000000
d0	0x0

CubeIDE – SFR okno



DELAY: zakasnitvena zanka



DELAY: Meritve STM32H750

```
////////////////////////////////////////////////////////////////////////////////
// Meritve
////////////////////////////////////////////////////////////////////////////////

//-------------- subs,bne -------------------------
//      ldr r5,=N
// ------------- odsek kode -----------------------
// tloop:  subs r5,r5,#1
//         bne  tloop
// ------------- konec kode -----------------------
/*
// Timings - usually in second or more repetition (on first one cycles are higher)
```

N	DWT_CYCCNT(1st)
50	56 (78)
100	106 (128)
200	206
500	506
1000	1006
64000	64006 (64028)

```
// Read DWT Counter before value
        ldr r0, [r1,#DWT_CYCCNT]

// ------------------------------
// Start of measurement code - use registers r3+ only !
// ------------------------------
tloop:  subs r5,r5,#1
        bne  tloop

// ------------------------------
//   End of measurement code
// ------------------------------

// Read DWT Counter after value
        ldr r2, [r1,#DWT_CYCCNT]

        sub r0,r2,r0    // Difference in r0
```

```
Comment: difference : r5 instructions are 16bit, r8 instructions are 32 bit, but both with same timing.
      if nop is added, for N=64000, results are 96030 and 96006
Conclusion: branch prediction is the main influencer here.
*/
```

Utripanje LED diod(e) – Zgradba programa

```
main:
        bl INIT_IO

loop:   bl LED_ON

        mov r0,#500
        bl DELAY

        bl LED_OFF

        mov r0,#500
        bl DELAY

        b loop
```

```
INIT_IO:
        push {r5,r6,lr}
        …
        pop {r5,r6,pc}

LED_ON:
        push {r5,r6,lr}
        …
        pop {r5,r6,pc}

LED_OFF:
        push {r5,r6,lr}
        …
        pop {r5,r6,pc}

DELAY:
        push {r1,lr}
        …
        pop {r1,pc}
```